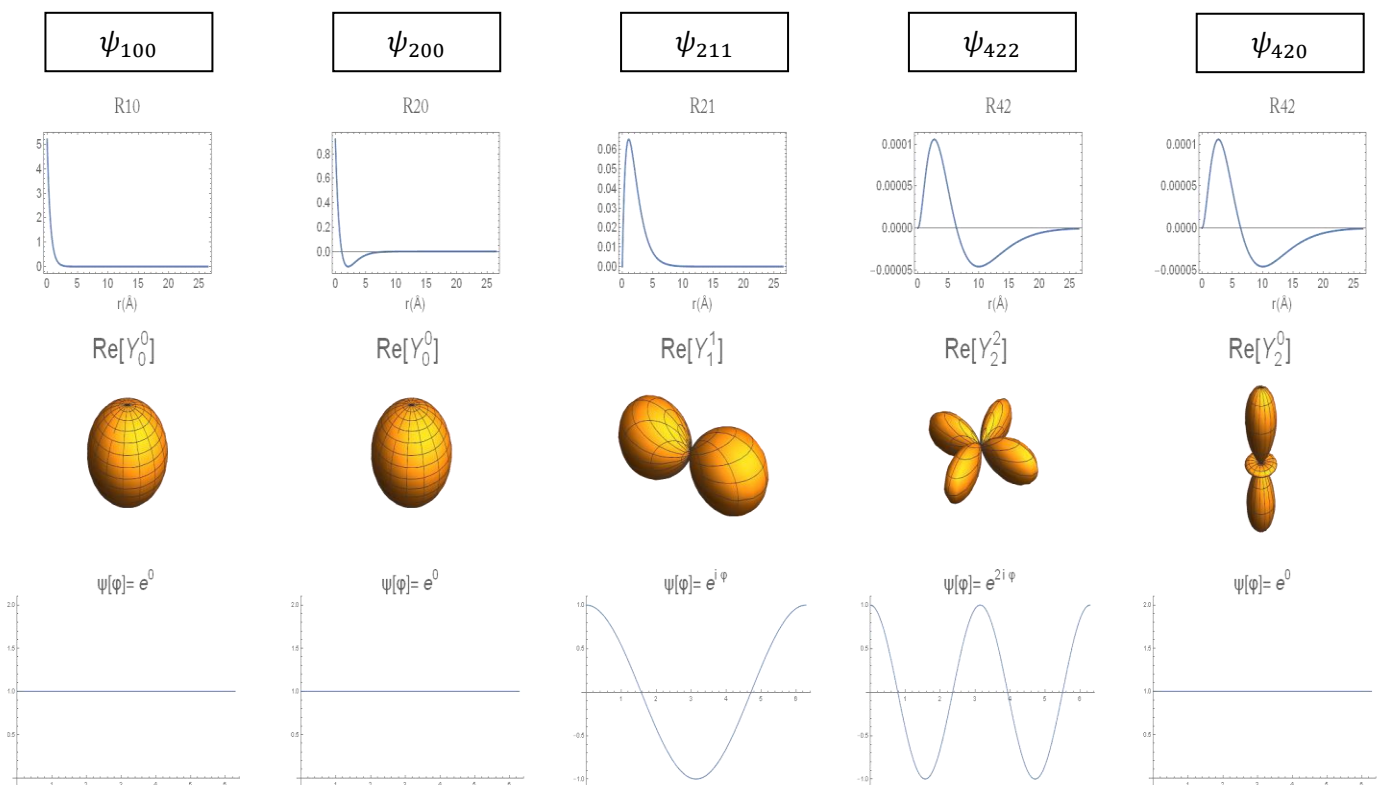


# Κβαντομηχανική Ι

## 5ο Σετ Ασκήσεων

### Άσκηση 1



### Άσκηση 2

Ζητά :

μέση τιμή της πιθανότητας της ακτινικής κατανομής  $\equiv$  προσδοκώμενη τιμή της ακτινικής κατανομής

$\Rightarrow$  μέση τιμή της πιθανότητας της ακτινικής κατανομής  $\equiv$  μέση τιμή της απόστασης  $r$

$\Rightarrow$  μέση τιμή της πιθανότητας της ακτινικής κατανομής  $\equiv \langle r \rangle = \frac{4\pi \int_0^\infty r r^2 |R(r)|^2 dr}{4\pi \int_0^\infty r^2 |R(r)|^2 dr} = \int_0^\infty r r^2 |R(r)|^2 dr$

Όπου κανονικοποιούμε, ώστε το αποτέλεσμά μας να είναι μια ακτίνα (το ολοκλήρωμα στον παρονομαστή είναι πάντα ίσο με 1)

$$\begin{aligned}
 \text{a) } \langle r \rangle_{1s} &= \int_0^\infty r r^2 |R_{10}|^2 dr \\
 &= \int_0^\infty r^3 \left( 2a_0^{-\frac{3}{2}} \right)^2 e^{-\frac{2r}{a_0}} dr \\
 &= 4a_0^{-3} \int_0^\infty r^3 e^{-\frac{2r}{a_0}} dr \\
 &= 4a_0^{-3} \left[ -\frac{1}{8} a_0 e^{-\frac{2r}{a_0}} (3a_0^3 + 6a_0^2 r + 6a_0 r^2 + 4r^3) \right] \Bigg|_0^\infty \\
 &= 0 - \frac{1}{2} a_0^{-3} (-a_0 3a_0^3) \\
 &= \frac{3a_0}{2}
 \end{aligned}$$

$$\begin{aligned}
 \text{b) } \langle r \rangle_{2s} &= \int_0^\infty r r^2 |R_{20}|^2 dr \\
 &= \int_0^\infty r^3 \left( \frac{1}{\sqrt{2}} a_0^{-\frac{3}{2}} \right)^2 \left( 1 - \frac{r}{2a_0} \right)^2 e^{-\frac{2r}{2a_0}} dr \\
 &= \frac{1}{2} a_0^{-3} \int_0^\infty r^3 \left( 1 - \frac{r}{a_0} + \frac{1}{4} \frac{r^2}{a_0^2} \right) e^{-\frac{r}{a_0}} dr \\
 &= \frac{1}{2} a_0^{-3} \left( \int_0^\infty r^3 e^{-\frac{r}{a_0}} dr - \int_0^\infty \frac{r^4}{a_0} e^{-\frac{r}{a_0}} dr + \int_0^\infty \frac{1}{4} \frac{r^5}{a_0^2} e^{-\frac{r}{a_0}} dr \right) \\
 &= \frac{1}{2} a_0^{-3} (6 - 24 + 30) a_0^4 \\
 &= 6a_0
 \end{aligned}$$

$$\begin{aligned}
 \text{c) } \langle r \rangle_{2p} &= \int_0^\infty r r^2 |R_{21}|^2 dr \\
 &= \int_0^\infty r^3 \left( \frac{1}{\sqrt{24}} a_0^{-\frac{3}{2}} \right)^2 \left( \frac{r}{a_0} \right)^2 e^{-\frac{2r}{2a_0}} dr \\
 &= \frac{1}{24} a_0^{-3} \int_0^\infty r^3 \frac{r^2}{a_0^2} e^{-\frac{r}{a_0}} dr \\
 &= \frac{1}{24} a_0^{-5} \int_0^\infty r^5 e^{-\frac{r}{a_0}} dr \\
 &= \frac{1}{24} a_0^{-5} 120 a_0^6 \\
 &= 5a_0
 \end{aligned}$$

$$\begin{aligned}
 \text{d) } \langle r \rangle_{3s} &= \int_0^\infty r r^2 |R_{30}|^2 dr \\
 &= \int_0^\infty r^3 \left( \frac{2}{\sqrt{27}} a_0^{-\frac{3}{2}} \right)^2 \left( 1 - \frac{2}{3} \frac{r}{a_0} + \frac{2}{27} \left( \frac{r}{a_0} \right)^2 \right)^2 e^{-\frac{2r}{3a_0}} dr \\
 &= \frac{16}{108} a_0^{-3} \left( \int_0^\infty r^3 e^{-\frac{2r}{3a_0}} dr - \int_0^\infty \frac{4r^4}{3a_0} e^{-\frac{2r}{3a_0}} dr + \int_0^\infty \frac{16}{27} \frac{r^5}{a_0^2} e^{-\frac{2r}{3a_0}} dr - \int_0^\infty \frac{8}{81} \frac{r^6}{a_0^3} e^{-\frac{2r}{3a_0}} dr \right. \\
 &\quad \left. + \int_0^\infty \frac{4}{729} \frac{r^7}{a_0^4} e^{-\frac{2r}{3a_0}} dr \right)
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{16}{108} a_0^{-3} a_0^4 \left( \frac{243}{8} - 243 + 810 - 1215 + \frac{2835}{4} \right) \\
 &= \frac{16}{108} a_0 \frac{729}{8} \\
 &= 13.5 a_0
 \end{aligned}$$

$$\begin{aligned}
 \text{e) } \langle r \rangle_{3d} &= \int_0^\infty r r^2 |R_{32}|^2 dr \\
 &= \int_0^\infty r^3 \left( \frac{4}{81\sqrt{30}} a_0^{-\frac{3}{2}} \right)^2 \left[ \left( \frac{r}{a_0} \right)^2 \right]^2 e^{-\frac{2r}{3a_0}} dr \\
 &= \frac{16}{30 \cdot 81^2} a_0^{-3} \int_0^\infty r^3 \frac{r^4}{a_0^4} e^{-\frac{2r}{3a_0}} dr \\
 &= \frac{16}{30 \cdot 81^2} a_0^{-7} \int_0^\infty r^7 e^{-\frac{2r}{3a_0}} dr \\
 &= \frac{16}{30 \cdot 81^2} a_0^{-7} 129170 a_0^8 \\
 &= 10.5 a_0
 \end{aligned}$$

## Άσκηση 3

$$x = r \sin(\theta) \cos(\varphi), \quad y = r \sin(\theta) \sin(\varphi), \quad z = r \cos(\theta)$$

$$r = \sqrt{x^2 + y^2 + z^2}, \quad \theta = \arccos\left(\frac{z}{r}\right), \quad \varphi = \arctan\left(\frac{y}{x}\right)$$

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}$$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial x} + \frac{\partial u}{\partial \varphi} \frac{\partial \varphi}{\partial x}$$

$$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial y} + \frac{\partial u}{\partial \varphi} \frac{\partial \varphi}{\partial y}$$

$$\frac{\partial u}{\partial z} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial z} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial z} + \frac{\partial u}{\partial \varphi} \frac{\partial \varphi}{\partial z}$$

$$\frac{\partial r}{\partial x} = \sin(\theta) \cos(\varphi), \quad \frac{\partial \theta}{\partial x} = \frac{1}{r} \cos(\theta) \cos(\varphi), \quad \frac{\partial \varphi}{\partial x} = -\frac{1}{r} \sin(\varphi) \sin(\theta),$$

$$\frac{\partial r}{\partial y} = \sin(\theta) \sin(\varphi), \quad \frac{\partial \theta}{\partial y} = \frac{1}{r} \cos(\theta) \sin(\varphi), \quad \frac{\partial \varphi}{\partial y} = \frac{1}{r} \cos(\varphi) \sin(\theta),$$

$$\frac{\partial r}{\partial z} = \cos(\theta), \quad \frac{\partial \theta}{\partial z} = -\frac{1}{r} \sin(\theta), \quad \frac{\partial \varphi}{\partial z} = 0$$

$$\frac{\partial u}{\partial x} = \sin(\theta)\cos(\varphi)\frac{\partial u}{\partial r} + \frac{1}{r}\cos(\theta)\cos(\varphi)\frac{\partial u}{\partial \theta} - \frac{1}{r}\sin(\varphi)\sin(\theta)\frac{\partial u}{\partial \varphi}$$

Άρα

$$\begin{aligned} \frac{\partial^2 u}{\partial x^2} &= \sin(\theta)\cos(\varphi)\frac{\partial}{\partial r}\frac{\partial u}{\partial x} + \frac{1}{r}\cos(\theta)\cos(\varphi)\frac{\partial}{\partial \theta}\frac{\partial u}{\partial \theta} - \frac{1}{r}\sin(\varphi)\sin(\theta)\frac{\partial}{\partial \varphi}\frac{\partial u}{\partial \varphi} \\ \frac{\partial^2 u}{\partial x^2} &= \left(\dots \frac{\partial^2 u}{\partial r^2} + \dots \frac{\partial u}{\partial \theta} + \dots + \frac{\partial^2 u}{\partial r\partial \theta} + \dots + \dots + \dots + \dots \frac{\partial^2 u}{\partial \varphi^2}\right) \\ \frac{\partial^2 u}{\partial y^2} &= \left(\dots \frac{\partial^2 u}{\partial r^2} + \dots \frac{\partial u}{\partial \theta} + \dots + \frac{\partial^2 u}{\partial r\partial \theta} + \dots + \dots + \dots + \dots \frac{\partial^2 u}{\partial \varphi^2}\right) \\ \frac{\partial^2 u}{\partial z^2} &= \left(\dots \frac{\partial^2 u}{\partial r^2} + \dots \frac{\partial u}{\partial \theta} + \dots + \frac{\partial^2 u}{\partial r\partial \theta} + \dots + \dots + \dots + \dots \frac{\partial^2 u}{\partial \varphi^2}\right) \end{aligned}$$

...Και με κάποιες «τετριμμένες» πράξεις, καταλήγουμε στο:

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = \frac{1}{r^2}\frac{\partial}{\partial r}\left(r^2\frac{\partial u}{\partial r}\right) + \frac{1}{r^2\sin\theta}\frac{\partial}{\partial \theta}\left(\sin\theta\frac{\partial u}{\partial \theta}\right) + \frac{1}{r^2\sin^2\theta}\frac{\partial^2 u}{\partial \varphi^2}$$

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